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6 May 53

WADC TECHNICAL REPORT 52-133

LAGRANGIAN INTERPOLATION

CLARENCE ROSS FLIGHT RESEARCH LABORATORY

SEPTEMBER 1952

WRIGHT AIR DEVELOPMENT CENTER

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WADC TECHNICAL REPORT 52-133

LAGRANGIAN INTERPOLATION

Clarence Ross Flight Research Laboratory

September 1952

RDO No. 468-1

Wright Air Development Center
Air Research and Development Command
United States Air Force
Wright-Patterson Air Force Case, Ohio

FOREWORD

This report was prepared by Dr. Clarence Ross, Project Scientist, Computation Branch, Flight Research Laboratory. Work was completed under RDO No. 468-1, Computation Services. The opportunity to write the report was due in part to the delay in delivery of OAPAC from Syracuse, New York. Because the elements tabulated were left in fraction form it was necessary to carry out a considerable amount of hand computation. Valuable assistance was afforded by Mr. Carl S. Fluke. Mr. Frank M. Williams and Rice P. White, Jr., A/lc checked most of the results.

ABSTRACT

A systematic method of constructing formulae, together with error terms, is given for use in interpolation, extrapolation, differentiation, and integration. Both closed and open type formulae are developed, using ordinates, and based on Lagrange's interpolation formulae for equal intervals. The procedure was suggested by Professor H. H. Aiken several years ago at Harvard University. The whole procedure may be extended easily to obtain cubature formulae and formulae used for surface fitting.

PUBLICATION REVIEW

This report has been reviewed and is approved.

FOR THE COMMANDING GENERAL:

ESLIP B. WILLIAMS

Colonel, USAF

Chief, Flight Research Laboratory

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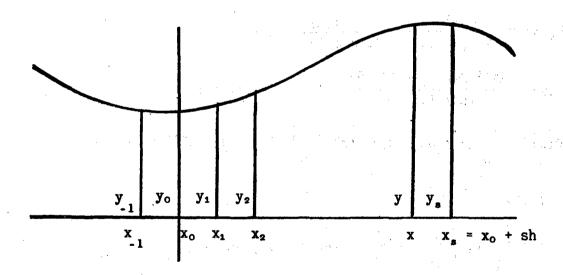
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LAGRANGIAN INTERPOLATION

The purpose of this paper is to apply Lagrange's interpolation formulae 1, 2, 3, 4 to derive polynomial approximating formulae (using ordinates) for interpolation, differentiation, and integration. Many of these formulae appear in the literature⁵ in terms of differences. Of course these differences may be expressed in terms of ordinates and in a sense the formulae which appear here are a recapitulation of elementary formulae found in Numerical Analysis. However, the simple derivations given here admit easy extensions to new formulae of great accuracy (exclusive of round-off error) to be used in connection with large scale high speed digital calculators. The number of ordinates employed in the formulae are indicated in the tables and include as many as ten.

LAGRANGE'S INTERPOLATION FORMULA

The following assumptions are made and the notation is more or less standard.



(a)
$$x = x_0 + uh$$
, $y_s = y(x_0 + sh) = y(x_s)$.

- (b) s, a, b are integers.
- (c) $a \le u \le b$, where u may be integral or not.
- (d) n + 1 = b a + 1 is the number of points through which the approximating polynomial (1) passes.
- (e) ξ lies between the smallest and the largest of the set x_s where s-a=0, 1, 2, ..., n.
- (f) $y^{(n+1)}$ (ξ) is familiar notation for the (n+1)st derivative evaluated at $x = \xi$.

Lagrange's formula may be written

(1)
$$y(x) = \sum_{s=a}^{b} C_{s-a}(x) y(x) + R(x)$$
 where

$$C_{\mathbf{z}}(\mathbf{x}) = \frac{\cdots \phi(\mathbf{x}) \cdots}{(\mathbf{x} - \mathbf{x}_{\mathbf{z}})\phi'(\mathbf{x}_{\mathbf{z}})} = \frac{\cdots \phi(\mathbf{u})}{(\mathbf{u} - \mathbf{s})\phi'(\mathbf{s})}$$
, and

(2)
$$R(x) = \frac{h^{n+1} \phi(u) y^{(n+1)}(\xi)}{(n+1)!}$$
 · Also by definition

$$\phi(x) = \prod_{s=a}^{b} (x + ah - x_s) = h^{n+1} \prod_{s=0}^{n} (u - s) = h^{n+1} \phi(u)$$

Proof of (1).

Assume
$$y = \sum_{s=a}^{b} \psi_s \frac{\phi(x)}{x-x_s} + R(x)$$
. Then for any particular

s (an integer) we have

$$y_s = \psi_s \lim_{x \to x_s} \frac{\phi(x)}{x - x_s} = \psi_s \phi'(x_s)$$
. Hence

$$\Psi_s = \frac{ys}{\phi'(x_s)}$$
 which leads to (1).

Proof 6 of (2).

Write
$$f(z) = R(z) - R(x) \frac{\phi(z)}{\phi(x)}$$
. It follows that $f = 0$ at $z = x$, x_s

for s - a = 0, 1, 2, 3,..., n. Hence by Rolle's theorem $f^{(n+1)}(\xi) = 0$.

Also it is apparent that $\phi^{(n+1)}(z) = (n+1)!$ Consequently

$$0 = R^{(n+1)}(\xi) - R(x) \frac{(n+1)!}{\phi(x)} \text{ so that } R(x) = \frac{\phi(x) R^{(n+1)}(\xi)}{(n+1)!}$$

Now by (1)

 $R^{(n+1)}(\xi) = y^{(n+1)}(\xi)$ which proves (2).

If b < u or u < a then (1) may be used to extrapolate y if we accept the error produced by taking ξ in (2) to lie in the interval between the least and greatest of the set x, x_a and again where s - a = 0, 1, 2, ..., n.

DIFFERENTIATION FORMULAE

By differentiating (1) and substituting $x = x_t$ where t is a particular s we get

(3)
$$y'(x_t) = \frac{1}{h} \sum_{s=a}^{b} C'_{s-a}y_s + R'(t)$$
 where

(4) R'(t) =
$$\frac{h^n \phi'(t) y^{(n+1)} (\xi)}{(n+1)!}$$

In order to prove (4) consider (2) which may be written

$$R(x) = \phi(x) y(x, x_s)$$
 since $\frac{y^{(n+1)}(\xi)}{(n+1)!}$ is a function of the set x, x_s

where s - a = 0, 1, 2,..., n. Hence $R' = \phi'y + \phi y'$ and since

$$\phi(x_t) = 0$$
 and $\phi'(x) = h^{n+1} \frac{d\phi}{du} \cdot \frac{du}{dx} = h^n \phi'(u)$ we have (4).

In order to simplify the remainder terms the derivative formulae are tabulated at the given ordinates only. Moreover not all these are tabulated since some may be implied. For example the 29 first derivative formulae imply 25 more. Indeed for s \neq t we have

$$C'_{s}(t) = \frac{1}{\phi'_{s}} \lim_{u \to t} \frac{\phi(u)}{(u-t)(u-s)} = \frac{1}{t-s} \cdot \frac{\phi'_{t}}{\phi'_{s}}, \text{ and}$$

$$C'_{n-s}(n-t) = \lim_{u \to n-s} \frac{u-n+s}{\phi(u)} \cdot \lim_{u \to n-t} \frac{\phi(u)}{(u-n+t)(u-n+s)}$$

$$= \lim_{u \to n-s} \frac{u-n+s}{\phi(n-u)} \cdot \lim_{u \to n-t} \frac{\phi(n-u)}{(u-n+t)(u-n+s)}$$

$$= -\lim_{u \to s} \frac{u-s}{\phi(u)} \cdot \lim_{u \to t} \frac{\phi(u)}{(u-t)(u-s)} = -\frac{1}{t-s} \cdot \frac{\phi'_{t}}{\phi'_{t}}.$$

Hence $C'_{s}(t) = -C'_{n-s}$ (n - t). The diagonal elements obey this relation also since

$$\sum_{s=0}^{n} C'_{s}(t) + \sum_{s=0}^{n} C'_{n-s}(n-t) = 0.$$

In order to obtain higher order differentiation formulae we may differentiate $y'=\frac{1}{h}$ C'_{s-a} y_s , omitting the remainder for a moment. Here y' and y_s are vectors while C'_{s-a} is a square matrix of order n + 1. Hence in general

(5)
$$y^{(n)} = \frac{1}{h^n} C'^n_{s-a} y_s$$
.

The remainder is obtained by differentiating $R(x) = \phi(x) y(x, x_s)$ as before. We have in general, using symbolic notation,

(6)
$$R^{(n)}(x) = [\phi(x) + y(x, x_n)]^{(n)}$$
.

Only the first term of $R^{(n)}(x)$ is retained i.e. $R^{(n)}(x) = \phi^{(n)}(x)$ y(x, x_s) unless this term vanishes. If $\phi^{(n)}(x) = 0$ then obviously the order of $R^{(n)}(x)$ is multiplied by h and is so indicated.

The implied differentiation formulae are obtained by using the relation $C_n^{(n)}$ (t) = $(-1)^{n+1}$ $C_{n-n}^{(n)}$ (n-t).

In the tabulation below $r^{(n)} = \frac{\phi^{(n)}}{(n+1)!}$

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QUADRATURE FORMULAE

We may obtain quadrature formulae by integrating (1) to get

(7)
$$\int_{b-k}^{b+1} y dx = h \sum_{s=a}^{b} C_{s-a}^{*} y_{s} + R^{*} \text{ where}$$

(8)
$$R^* \leq \frac{h^{n+2} y^{(n+1)}(\xi)}{(n+1)!} \int_{-k}^{1} \phi(u+n) du$$

(unless the last integral vanishes) and where

$$C_s^* = \int_{-k}^{1} C_s(u + n) du = \frac{1}{\phi'_s} \int_{n-k}^{n+1} \frac{\phi(u) du}{u - s}$$

In order to prove (8) consider again and a second a second and a second a second and a second a second and a second and a second and a

 $R(x) = \phi(x) y(x, x_{\underline{x}}')$ from which

$$R^* = h^{n+2} \int_{u=-k}^{1} \phi(u + n) y(x, x_s) du$$

Now $\phi(u + n) = \prod_{s=0}^{n} (u + s)$ which is monotonic increasing for u > 0.

By the Mean Value Theorem we may therefore write

$$\int_{0}^{1} \phi(u+n) \ y(x, x_{s}) \ du = \frac{y^{(n+1)} (\xi_{1})}{(n+1)!} \int_{0}^{1} \phi(u+n) \ du \ \text{where}$$

 $0 < \mathcal{E}_1 < 1$. Again by Rolle's Theorem since $\phi(u + n)$ is continuous and vanishes at u = 0, -1, there is a point $-1 < \eta < 0$ such that $\phi'(u + n) = 0$.

Consequently in the interval $\eta \le u \le 0$, $\phi(u + n)$ is monotonic increasing so that we may write

$$\int_{\eta}^{\circ} \phi(u + n) \ y(x, x_s) \ du = \frac{y^{(n+1)} (\xi_2)}{(n+1)!} \int_{\eta}^{\circ} \phi(u + n) \ du \ where$$

 $\eta < \xi_2 < 0$. If $y^{(n+1)}$ (ξ) is the larger of $y^{(n+1)}$ (ξ_1), $y^{(n+1)}(\xi_2)$ then we may write

$$\int_{\eta}^{1} \phi(u + n) \ y(x, x_s) \ du \le \frac{y^{(n+1)}(\xi)}{(n+1)!} \int_{\eta}^{1} \phi(u + n) \ du \ where$$

η < ξ < 1.

Continuing for the interval $-1 \le u < \eta$ we find that $\phi(u + n)$ is monotonic decreasing so that we may write

$$\int_{-1}^{\eta} \phi(u+n) y(x,x_s) du = \frac{y^{(n+1)}(\xi_s)}{(n+1)!} \int_{-1}^{\eta} \phi(u+n) du \text{ where}$$

 $-1 < \xi_s < \eta$. Therefore we may write

$$\int_{-1}^{1} \phi(u + n) \ y(x, x_s) \ du = \frac{1}{(n+1)!} \left[y^{(n+1)} (\xi_s) \right]_{-1}^{\eta} +$$

$$y^{(n+1)}(\xi_2)$$
 $\int_{\eta}^{\bullet} + y^{(n+1)}(\xi_1) \int_{\bullet}^{1} 1 \le \frac{y^{(n+1)}(\xi)}{(n+1)!} \int_{-1}^{1} \phi(u+n) du$

where $-1 < \xi < 1$ and $y^{(n+1)}$ (ξ) is the largest of $y^{(n+1)}$ (ξ_1), $y^{(n+1)}$ (ξ_2), $y^{(n+1)}$ (ξ_3). Since the polynomial ϕ vanishes at $-u = 0, 1, 2, \ldots, n$ we find (8) by continuing in this way.

The condition $\int_{-k}^{1} \phi(u+n) du \neq 0$ cannot be relaxed. However because of this condition no formula will be lost. For consider

$$\phi_{s-1, n-1} C_{s-1, n-1}^* = \int_{n-k-1}^{n+1-1} \frac{\phi(u) du}{(u-s+1) (u-n)} = \int_{n-k}^{n+1} \frac{\phi(u-1) du}{(u-s) (u-n-1)}$$

$$= \int_{n-k}^{n+1} \frac{\phi(u) du}{u(u-s)} . \text{ Hence we have}$$

$$\phi'_{s} C'_{s} - s \phi'_{s-1, n-1} C'_{s-1, n-1} = \int_{n-k}^{n+1} \left[\frac{\phi(u)}{u-s} - \frac{s \phi(u)}{u(u-s)} \right] du$$

$$= \int_{n-k}^{n+1} \frac{\phi(u) du}{u} \phi'_{e} C'_{o}$$

and since $s \phi'_{s-1, n-1} = \phi'_{s}$ we have

(9)
$$C_s^* = \frac{\phi'_o}{\phi'_s} C_o^* + C_{s-1, n-1}^*$$

The $C_{s-1, n-1}^*$ refers to that value immediately above C_{s-1}^* in the tables below. Of course

$$\phi'_{0}$$
 $C_{0}^{*} = \int_{-k}^{l} \phi_{n-1} (u + n) du$ where the integral is on the line

immediately above C_0^* in the tables. If this integral vanishes we have $C_s^* = C_{s-1, n-1}^*$ by (9), for $s \neq 0$, and therefore the formula is repeated.

It is easy to see that this integral cannot vanish twice in succession. By taking l=1 we obtain open quadrature formulae and by taking $l\leq 0$ we obtain closed quadrature formulae. Because of symmetry the implied quadrature formulae double to number of formulae listed below. For example if C_{\bullet}^{*} is replaced by $C_{n-\bullet}^{*}$ in a formula, for extrapolating ahead we shall replace it by one which extrapolates backward. The remainders may be different because the intervals are different for ξ .

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5	:						$\frac{198721}{60480}$	1152169 120960	47738393 1814400	28416361 453600
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5	ij				1901	2641 480	235183 20160	- 29 <u>6053</u> 13440	862303 22680	222386081 3628800
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ŧ						1607 448	- 35723 4480	580969 22400	136746
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* 5	ລິ	144	- 1175 - 288	16225	$-\frac{487225}{24192}$	169555	8679625
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$\int_{-6}^{1} \varphi(u+n) du$		3679 <u>9</u>	1046689	2036097	131427457
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* o				$\frac{2162377}{518400}$	13286371 1036800
₽			2485 640	$\frac{2667133}{259200}$	4720471 129600
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$\int_{-7}^{1} \phi(u+n) du$		506368 45	506368 5	32814080	$\int_{-8}^{1} \varphi(u+n) du$		2082753 20	43928811
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TR 52	2–133				45		

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TR 5	2–133	3			4	8		

$\int_{-4}^{-3} \phi(u+n) dx$	191	249 <u>7</u> 90	2497	90817 132	$\int_{-5}^{4} \phi(u+n) du$	3233	- 249 <u>T</u>	13985
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APPLICATION OF FORMULAE

Desirable closed formulae are easily seen to be No's 64, 78, 88, and 94. Some caution should be used when the 8-strip formula is employed for since some of its coefficients are negative the round-off error may appear excessive. Although some of the coefficients are negative, neverthe-less, open formulae No's 27, 40, 49, and 54 show considerable appeal. For example No. 40 was employed in A.F. Problem No. 19 at Harvard Computation Laboratory.

Very little can be said in favor of increasing the error in order to simplify the coefficients when the numerical operations are performed on a large scale digital electronic calculator. Consequently Weddle's Rule, Hardy's Formula, Shovelton's Rule, etc. will not be introduced here.

Often it is necessary to change the mesh interval when integrating a system of differential equations. Formula (1) may be used to generate a set of formulae to cut such an interval. Obviously no special formulae are necessary to double an interval.

It is interesting to note that by decreasing the mesh size indefinitely and at the same time keeping all the ordinates (an infinite number in a finite interval) we are led to the cardinal interpolation function mentioned in AFTR No. 6581 by F. W. Bubb.

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